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Publicatii (h-index = 26)

Articole in jurnale cu referenti

1. Chevalier, P., Martin, J.-C., Bazile, C., Isableu, B., Tapus, A. (2016) " Joint Attention in Human-Robot Interaction: Impact of Sensory Preferences of Individuals with Autism", International Journal on Social Robotics (IJSR) (under review)
2. Aly, A., and **Tapus, A.** (2016) "Multimodal Adapted Robot's Behavior Synthesis within a Narrative Human-Robot Interaction", IEEE Transactions on Robotics (under review)
3. Rossi, S., Ferland, F., Tapus, A. (2017) "User Profiling and Behavioral Adaptation for HRI: a Survey", Pattern Recognition Letters (under review)
4. Chevalier, P., Martin, J.-C., Bazile, C., Isableu, B., **Tapus, A.** (2016), "Exploratory Study for Customized Human-Machine Interaction for People Suffering of ASD", In Autonomous Robots, Special Issue on Assistive and Rehabilitation Robotics, May 2016 (impact factor: 2.07)
5. Aly, A., and **Tapus, A.** (2015) "An Integrated Model for Generating a Combined Verbal and Non-Verbal Behavior Adapted to Personality Dimensions in Human-Robot Interaction", Autonomous Robots, July 2015 (impact factor: 2.07)
6. Mozos, O., M., Galindo, C., and **Tapus, A.** (2015) "Computer-Based Intelligent Technologies for Improving the Quality of Life", Guest Editorial, IEEE Journal of Biomedical and Health Informatics, 2015 (impact factor: 1.98)
7. Dang, T-H. H., and **Tapus, A.** (2015) "Stress Game - The Role of Motivational Robotic Assistance in Reducing User's Task Stress", International Journal of Social Robotics, 2015 (impact factor: 1.207)
8. Ramaswamy A., Monsuez, B., and **Tapus, A.** (2014) "Solution Space Modeling for Robotic Systems", JOSER, 5(1), pp. 89-96, ISSN: 2035-3928.
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- 34.** Cruz, A., and **Tapus, A.** (2016) "Influence of user's personality on task execution when reminded by a robot", In Proceedings of International Conference on Social Robotics (ICSR 2016), Kansas City, USA, November 2016
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- 40.** Chevalier, P., Martin, J.-C., Bazile, C., Isableu, B., **Tapus, A.** (2015) "Profilage Visuel et Proprioceptif pour l'Elaboration des Interactions Homme-Robot Adaptées", In Journée "Sciences du Mouvement" (FEDEV 2015), Paris, France, December 2015, **Awarded Best Student Paper Award**.
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- 55.** Ammi, M., Demulier, V., Caillou, S., Gaffary, Y., Ballik, Y., Martin, J.-C., and **Tapus, A.** (2015) "Haptic Human-Robot Affective Interaction in a Handshaking Social Protocol", In Proceedings of IEEE Human-Robot Interaction Conference (HRI), Oregon, USA, March 2015 (25% acceptance rate).
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- 105.** **Tapus, A.**, Tapus C. and Matarić, M., J. (2009) “Music Therapist Robot: A Solution for Helping People with Cognitive Impairments”, Proceedings of the IJCAI 2009 Workshop on Intelligent Systems for Assisted Cognition, Pasadena, California, 12 July 2009.
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- 109.** **Tapus, A.** and Matarić, M., J. (2007) “Towards Active Learning for Socially Assistive Robots”, In Proceedings of the Neural Information Processing Systems (NIPS) 2007 Workshop: Robotics Challenges for Machine Learning, Vancouver, Canada, December 2007.
- 110.** Bur, A., **Tapus, A.**, Ouerhani, N., and Hugli, H. (2006) “Robot Navigation by Panoramic Vision and attention Guided Features”, In Proceedings of the 18th International Conference on Pattern Recognition (ICPR), Hong Kong, China, August 2006.

- 111.** Tapus, A. and Siegwart, R. (2006) "Fingerprints of Places: A Model of Hippocampal Place Cells", In Proceedings of the IEEE International Conference on Robotics and Automation (ICRA), Orlando, Florida, U.S.A., May 2006.

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- 113.** Aly, A., and **Tapus, A.** (2012), "How to Infer the Intention of Human while Interacting with a Robot?", In 5th Workshop for Young Researchers on Human-Friendly Robotics, Brussels, Belgium, November, 2012.
- 114.** Dang, T. H. H., and **Tapus, A.** (2012), "Stress Game - In perspectives of Motivational Robotic Assistance", In Proceedings of IROS 2012 Workshop on Motivational Aspects of Robotics in Physical Therapy, Algarve, Portugal, October, 2012.
- 115.** Dang, T. H.H., and **Tapus, A.** (2012), "Robot Personality Design for an Appropriate Response to the Human Partner", In Proceedings of Ro-Man 2012 Workshop on Feedback Readability for Robots, Paris, France, September, 2012
- 116.** Aly, A., and **Tapus, A.** (2011), "Speech-Driven Arm Gestures Synthesis in Multimodal Human-Robot Interaction", In *4th Workshop for Young Researchers on Human-Friendly Robotics*, Twente, The Netherlands, November, 2011.
- 117.** Aly, A., and **Tapus, A.** (2010), "Gestures Imitation with a Mobile Robot in the Context of Human-Robot Interaction (HRI) for Children with Autism", In *3rd Workshop for Young Researchers on Human-Friendly Robotics*, Tübingen, Germany, October, 2010.
- 118.** Chetouani, M., Wu, Y. H., Jost, C., Le Pevedic, B., Fassert, C., Cristancho-Lacroix, V., Lassialle, S., Granata, C., **Tapus, A.**, Duhaut, D., Rigaud, A. S. (2010) "Cognitive Services for Elderly People: The ROBADOM project", In *Proceedings of the European Conference on Cognitive Ergonomics 2010 (ECCE 2010)*, Workshop on "Robots That Care", Delft, The Netherlands, August 2010.
- 119.** **Tapus, A.** and Chetouani, M. (2010) "ROBADOM: The Impact of a Domestic Robot on the Psychological and Cognitive State of the Elderly with Mild Cognitive Impairment", In *Proceedings of the Second International Symposium on Quality of Life Technology Intelligent Systems for Better Living*, Las Vegas, USA, June, 2010.
- 120.** Erden, S. and **Tapus, A.** (2010) "Postural expressions of emotions in a humanoid robot for assistive applications", *Robotics: Science and Systems (RSS) Workshop on Learning for Human-Robot Interaction Modeling*, Zaragoza, Spain, June, 2010.

- 121.** **Tapus, A.** and Matarić, M., J. (2009) “Improving the Quality of Life of People with Dementia through the Use of Socially Assistive Robots”, *Proceedings of the First International Symposium on Quality of Life Technology Intelligent Systems for Better Living*, Pittsburgh, USA, June 30 – July 1, 2009.
- 122.** **Tapus, A.** (2008) “Long-term learning and adaptation in intelligent personal robotics”, In *Machine Learning: Theory, Applications, Experiences Workshop for Women in Machine Learning*, Vancouver, Canada, December 2008.
- 123.** **Tapus, A.** and Matarić, M., J. (2008) “Socially Assistive Robotic Music Therapist for Maintaining Attention of Older Adults with Cognitive Impairments”, In *Proceedings of AAAI Fall Symposium AI in Eldercare: New Solutions to Old Problem*, Washington, DC, USA, November 7-9, 2008.
- 124.** **Tapus, A.** and Matarić, M., J. (2008) “Active Learning for Socially Assistive Robotics for Stroke Rehabilitation and Dementia Care”, *Robotics: Science and Systems (RSS) Workshop on Interactive Robot Learning*, Zurich, Switzerland, June, 2008.
- 125.** **Tapus, A.**, Fasola, J., and Matarić, M., J. (2008) “Cognitive Assistance and Physical Therapy for Dementia Patients Using Socially Assistive Robots”, *ICRA Workshop on Social Interaction with Intelligent Indoor Robots*, Pasadena, USA, May, 2008.
- 126.** **Tapus, A.**, Fasola, J., and Matarić, M., J. (2008) “Socially Assistive Robots for individuals suffering from dementia”, *HRI Workshop on Robotic Helpers: User Interaction, Interfaces and Companions in Assistive and Therapy Robotics*, Amsterdam, The Netherlands, March, 2008.
- 127.** **Tapus, A.** and Matarić, M., J. (2008) “Socially Assistive Robots: The Link between Personality, Empathy, Physiological Signals, and Task Performance”, *AAAI Spring Symposium*, Palo Alto, Stanford, USA, March, 2008.
- 128.** Matarić, M., J., **Tapus, A.**, and Feil-Seifer D. (2007) “Personalized Socially Assistive Robotics”, *Workshop on Intelligent Systems for Assisted Cognition*, Rochester, New York, USA, October, 2007.
- 129.** **Tapus, A.** and Matarić, M., J. (2007) “Emulating Empathy in Socially Assistive Robotics”, *AAAI Spring Symposium*, Palo Alto, Stanford, USA, March, 2007.
- 130.** **Tapus, A.** and Matarić, M., J. (2006) “Therapist Robot Behavior Adaptation for Post-Stroke Rehabilitation Therapy”, In *Machine Learning: Theory, Applications, Experiences Workshop for Women in Machine Learning*, San Diego, U.S.A., October 2006.
- 131.** Matarić, M., J. and **Tapus, A.** (2006) “The Promises and Challenges of Socially Assistive Robotics”, *50th Anniversary AI Summit*, Monte Verita, Switzerland, July 2006.

- 132.** Siegwart, R., Vasudevan S., and **Tapus, A.** (2004) “From Geometric to Cognitive Maps – A Key Element for Personal Robots”, *18th IFIP World Computer Congress*, Toulouse, France, August 2004, pp. 755-760.

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- 133.** **Tapus, A.** (2007) “Socially Assistive Robotics: Active Learning for User Task Performance Improvement”, In *Assistive Technologies: Rehabilitation and Assistive Robotics Workshop, Proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, San Diego, CA, USA, October, 2007.
- 134.** **Tapus, A.** (2007) “The Future of Therapy and Personal Care Robots: Towards Socially Assistive Robotics”, In *Robotic Technology for Rehabilitation Workshop, Proceedings of the IEEE International Conference on Robotics and Automation (ICRA)*, Roma, Italy, April 2007.
- 135.** **Tapus, A.** and Matarić, M., J. (2006) “User-Robot Personality Matching for Post-Stroke Rehabilitation Therapy”, In *Socially Assistive Robotics Workshop, Proceedings of the Robotics: Science and Systems Conference (RSS)*, Philadelphia, Pennsylvania, U.S.A., August 2006.
- 136.** **Tapus, A.** (2006) “From Human-like Robot Navigation to Human-Robot Interaction”, In *Cognitive Robots and Systems Workshop, Proceedings of the IEEE International Conference on Robotics and Automation (ICRA)*, Orlando, Florida, U.S.A., May 2006.

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- 137.** **Tapus, A.** (2011) “Towards Personalized Human-Robot Interaction” *HDR Dissertation (Habilitation a Diriger des Recherches)*, Computer Science Department, Pierre and Marie Curie University (UPMC), Paris, France, July 2011.
- 138.** **Tapus, A.** (2005) “Topological SLAM - Simultaneous Localization and Mapping with Fingerprints of Places” *PhD Dissertation*, Computer Science and Systems Engineering Department, Swiss Federal Institute of Technology Lausanne (EPFL), Switzerland, October 2005.
- 139.** **Tapus, A.** (2002) “Markov Decision Processes Use for Mobile Robot Actions Planning and Execution.” *Masters Degree Report in Computer Science*, Joseph Fourier University, Grenoble, France.

Granturi si contracte de cercetare

- CHIST-ERA grant "Orchestration of adaptive mobile machines learning from complex environments (LEARNet)", Spain, ENSTA ParisTech (France), Poland, Austria, and Romania, submitted 17/01/2016 (under review 2017)
- FUI grant “Projet Intelligence Robotique pour le Monitoring et l’Informatisation des Soins (IRMIS)”, PI: Extia, Co-PI: Robosoft, Medsys, Centre Hospitalier de Troye, A. Tapus (ENSTA- ParisTech) (under review 2017)
- Project " Physiological state, deception and trust detection in HRI by using a mixture of Thermal and RGB-D cameras" (2016), PI: Prof. Adriana Tapus (ENSTA), student thesis: David Octavian IACOB, total € 109 000
- Digiteo Project "Haptic Emotional Robot Experiments with Sensitive Body" (HEROES) (2015), PI: Prof. Adriana Tapus (ENSTA), Prof. Mehdi Ammi (LIMSI, Paris XI) and Dr. Moustapha Hafez (CEA), total € 109 000
- Digiteo Project Conférence "International Conference on Social Robotics" (2015), PI: Prof. Adriana Tapus (ENSTA) and Prof. Jean-Claude Martin (LIMSI, Paris XI), total € 5000
- DGA Fellowship "Conception de Briques Génériques Logicielles et Patrons d'Architectures pour les Applications Critiques intégrant des processus d'Autonomie Décisionnelle", PI : Prof. Bruno Monsuez (ENSTA) and Prof. Adriana Tapus (ENSTA), total € 109 000
- EU Horizon2020 “ENRICHME: Enabling Robot and assisted living environment for Independent Care and Health Monitoring of the Elderly”, PI: Roberto Rosso (TESAN), PI: A. Tapus (ENSTA-ParisTech), PI: N. Bellotto (UoL), PI: P. Baratinni (KONTOR), PI: V. Dupourque (Robosoft), PI: A. van Berlo (STICHTING SMART HOMES), PI: V. Gower (FONDAZIONE DON CARLO GNOCCHI ONLUS), PI: K. Wieczorowska-Tobis (PUMS), PI: D. Wieczorek (OPS), PI: P. Hobson (Lace Housing), PI: C. Prouskas (Aktios), total € 3 991 940. Jan 2015 – Jan 2018. PSPC for “ROMEO 2”, PI: D. Filliat (ENSTA-ParisTech), co-PI: A. Tapus, total € 509 309. Sept 2012 – Sept 2015.
- Region IdF Project HANDICAP " Proprioceptive, Kinematic, Socially and Individualized Human-Machine Interaction" (HEROES) PI: Prof. Adriana Tapus (ENSTA), Prof. Brice Isableu (LIMSI, Paris XI) and Prof. Jean-Claude martin (LIMSI, Paris XI) total € 109 000
- PSPC for “ROMEO 2”, PI: D. Filliat (ENSTA-ParisTech), co-PI: **A. Tapus**, total € 237 309. Sept 2012 – Sept 2015.
- ANR-Chaires d’Excellence (Excellent Researchers) for “HRIAA - Human-Robot Interaction for Assistive Applications”, PI: **A. Tapus** (ENSTA-ParisTech), total € 484 200 €. Dec 2009 – Dec 2013.

- ANR-Carotte grant for “PACOM: Panoramic and Active Cameras for Semantic Object Mapping”, PI: D. Filliat (ENSTA-ParisTech), co-PIs: **A. Tapus** (ENSTA-ParisTech), R. Benosman (UPMC), J.-C. Mammana (Gostai), total € 349 709. Sept 2009 – Sept 2012.
 - UPMC grant for “Intelligent Systems for Multi-perceptual Stimulation for Children with Developmental Disorders – MULTI-STIM”, PI: M. Chetouani (UPMC), co-PIs: **A. Tapus** (ENSTA-ParisTech), D. Cohen (UPMC), J. Xavier (GH Pitié-Salpêtrière), M. Plaza (GH Pitié-Salpêtrière), L. Chaby (Pierre Descartes University), total € 150,000. Mar 2010 – Mar 2011.
 - ANR-TecSan (Program for Technology for Health and Autonomy) grant for “ROBADOM: Impact of a robot “butler” at home on psychological and cognitive state of the elderly with mid cognitive impairment”, PI: Anne-Sophie RIGAUD (BROCA Hospital), co-PIs: **A. Tapus** (ENSTA-ParisTech), M. Chatouani (UPMC), D. Duhaut (Université de Bretagne Sud), V. Dupourque (Robosoft), total € 736,316. Sept 2009 – Sept 2011.
 - NSF Workshop Travel grant for “HRI Pioneers Workshop 2008”, PI: J. Burke, co-PI: **A. Tapus**, total \$30,448, Jan 2008 – Jan 2009.
 - Netherlands Organisation for Scientific Research (NWO) Travel grant for “HRI Pioneers Workshop 2008”, PI: **A. Tapus**, co-PI: M. Neerincx, total €5,000, Jan 2008.
 - Institutional Review Board (IRB) Proposal for “Assessing Socially Assistive Robotics as Social and Cognitive Aides for the Elderly”, PI: M. J. Matarić, co-PI: **A. Tapus** and M. Gatz, Oct 2007 – Oct 2010
 - NIH Aging and Disability Resource Center grant for “Assessing Socially Assistive Robotics as Social and Cognitive Aides for the Elderly”, PI: M. J. Matarić, key personnel: **A. Tapus**, total \$80,000, Jun 2007- Jun 2008.
 - NSF Human-Robot Interaction Program grant for “Personalized Assistive Human-Robot Interaction: Validation in Socially-Assisted Post Stroke Rehabilitation”, PI: M. J. Matarić, co-PI: C. Winstein, key personnel: **A. Tapus**, total \$450,000, Sept 2007- Aug 2010.
 - Institutional Review Board (IRB) Proposal for “Hands-Off Robot Therapist for Post-Stroke Rehabilitation” (HS-06-00628), PI: C. Winstein, co-PI: **A. Tapus** and M. J. Matarić, Jun 2007 – Jun 2010.
 - EU grant for “Bayesian Inspired Brain and Artefacts (BIBA)” (IST-2001-32115), PI: Pierre Bessiere, co-PI EPFL: Roland Siegwart, key personnel EPFL: **A. Tapus** and G. Ramel, total €1,640,000, Nov 2001 – Nov 2005.
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